PELCO

CAMERA

Supported version

TOP Design Studio

V1.4.3.2 or higher



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We want to thank our customers who use the Touch Operation Panel.

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Refer to this section to check the addresses which can communicate with an external device.



1. System configuration

The system configuration of TOP and "PELCO: CAMERA" is as follows:

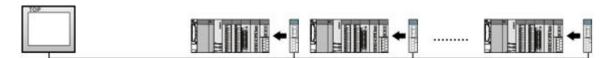
Series	Module	Link I/F	Communication method	System setting	Cable
PELCO: CAMERA	1	1	RS-232C RS-422,485	3.1 Settings example 1	4.1. Cable table 1

■ Connection configuration

• 1:1 connection (one MASTER and one TOP) connection



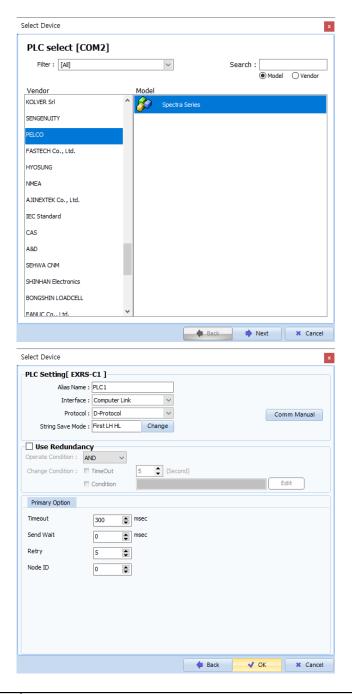
• 1:N (one TOP and multiple external devices) connection – configuration which is possible in RS422/485 communication.





2. External device selection

■ Select a TOP model and a port, and then select an external device.



Settings		Contents			
TOP	Model	Check the TOP display and	Check the TOP display and process to select the touch model.		
External device	Vendor	Select the vendor of the external device to be connected to TOP. Select "PELCO".			
	PLC	Select an external device t	Select an external device to connect to TOP.		
		Model Interface Protocol			
		CAMERA Computer Link D-Protocol			
		Please check the system configuration in Chapter 1 to see if the external device you want to connect is a model whose system can be configured.			



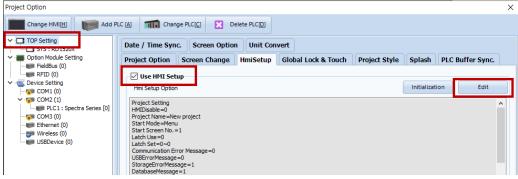
3. TOP communication setting

The communication can be set in TOP Design Studio or TOP main menu. The communication should be set in the same way as that of the external device.

3.1 Communication setting in TOP Design Studio

(1) Communication interface setting

- [Project > Project Property > TOP Setting] → [Project Option > "Use HMI Setup" Check > Edit > Serial]
 - Set the TOP communication interface in TOP Design Studio.





Items	ТОР	External device	Remarks		
Signal Level (port)	RS-485	RS-485 (COM1/COM2)			
,	(COM1/COM2)				
Baud Rate	384				
Data Bit	8				
Stop Bit	1				
Parity Bit	NONE				

* The above settings are examples recommended by the company.

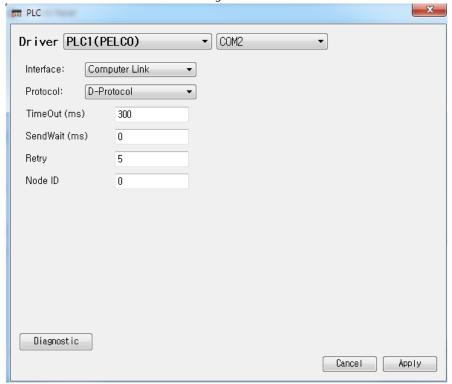
Items	Description
Signal Level	Select the serial communication method between the TOP and an external device.
Baud Rate	Select the serial communication speed between the TOP and an external device.
Data Bit	Select the serial communication data bit between the TOP and an external device.
Stop Bit	Select the serial communication stop bit between the TOP and an external device.
Parity Bit	Select the serial communication parity bit check method between the TOP and an external device.



(2) Communication option setting

■ [Project > Project Property > Device Setting > COM > "PLC1 : **PELCO : CAMERA**]

Set the options of the communication driver in TOP Design Studio.

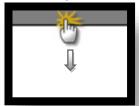


Items	Settings	Remarks
Interface	Select "Computer Link".	Refer to "2.
Protocol	Select the communication protocol between the TOP and an external device.	External device selection".
TimeOut (ms)	Set the time for the TOP to wait for a response from an external device.	
SendWait (ms)	Set the waiting time between TOP's receiving a response from an external device and sending the next command request.	
Retry	Retry attempts	
Node ID	Device number	



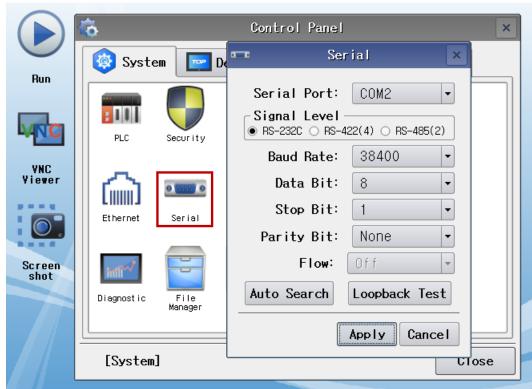
3.2. Communication setting in TOP

- * This is a setting method when "Use HMI Setup" in the setting items in "3.1 TOP Design Studio" is not checked.
- Touch the top of the TOP screen and drag it down. Touch "EXIT" in the pop-up window to go to the main screen.



(1) Communication interface setting

■ [Main Screen > Control Panel > Serial]



Items	TOP	External device	Remarks	
Signal Level (port)	RS-485	RS-485		
Baud Rate	38400			
Data Bit	8			
Stop Bit	1			
Parity Bit	nor			

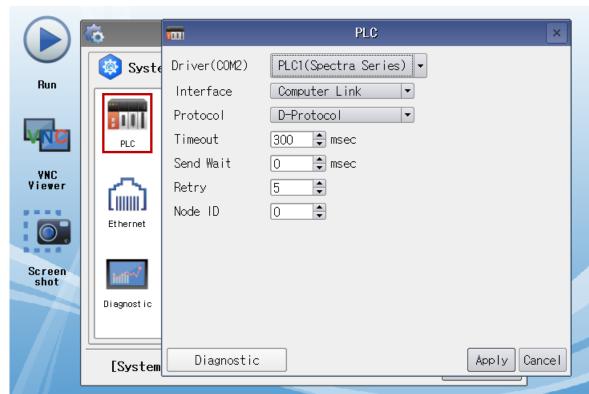
^{*} The above settings are setting examples recommended by the company.

Items	Description			
Signal Level	Select the serial communication method between the TOP and an external device.			
Baud Rate	Select the serial communication speed between the TOP and an external device.			
Data Bit	Select the serial communication data bit between the TOP and an external device.			
Stop Bit	Select the serial communication stop bit between the TOP and an external device.			
Parity Bit	Select the serial communication parity bit check method between the TOP and an external device.			



(2) Communication option setting

■ [Main Screen > Control Panel > PLC]



Items	Settings	Remarks
Interface	Select "Computer Link".	Refer to "2. External
Protocol	Select the communication protocol between the TOP and an external device.	device selection".
TimeOut (ms)	Set the time for the TOP to wait for a response from an external device.	
SendWait (ms)	Set the waiting time between TOP's receiving a response from an external device	
	and sending the next command request.	
Retry	Retry attempts	
Node ID	Device number	



3.3 Communication diagnostics

- Check the interface setting status between the TOP and an external device.
- Touch the top of the TOP screen and drag it down. Touch "EXIT" in the pop-up window to go to the main screen.
- Check if the COM port settings you want to use in [Control Panel > Serial] are the same as those of the external device.
- Diagnosis of whether the port communication is normal or not
- Touch "Communication diagnostics" in [Control Panel > PLC].
- The Diagnostics dialog box pops up on the screen and determines the diagnostic status.

ОК	Communication setting normal				
Time Out Error	Communication setting abnormal				
	- Check the cable, TOP, and external device setting status. (Reference: Communication diagnostics sheet)				

■ Communication diagnostics sheet

- If there is a problem with the communication connection with an external terminal, please check the settings in the sheet below.

Items	Con	Contents		eck	Remarks
System	How to connect the s	ystem	OK	NG	1 Contains configuration
configuration	Connection cable nam	ne	OK	NG	1. System configuration
TOP	Version information	OK	NG		
	Port in use		OK	NG	
	Driver name		OK	NG	
	Other detailed setting	S	OK	NG	
	Relative prefix	Project setting	OK	NG	
		Communication diagnostics	ОК	NG	2. External device selection3. Communication setting
	Serial Parameter	Transmission Speed	ОК	NG	
		Data Bit	OK	NG	
		Stop Bit	OK	NG	
		Parity Bit	OK	NG	
External device	CPU name	OK	NG		
	Communication port	OK	NG		
	Protocol (mode)	OK	NG		
	Setup Prefix	OK	NG		
	Other detailed setting	OK	NG		
	Serial Parameter	Transmission Speed	OK	NG	
		Data Bit	OK	NG	
		Stop Bit	OK	NG	
		Parity Bit	OK	NG	
	Check address range		OK	NG	5. Supported addresses (For details, please refer to the PLC vendor's manual.)



4. Cable table

This chapter introduces a cable diagram for normal communication between the TOP and the corresponding device. (The cable diagram described in this section may differ from the recommendations of "PELCO CAMERA")

■ RS-232C (1:1 connection)

TC)P			External device		
Pin	Signal	Pin	Cable connection	Signal name		
arrangement*Note 1)	name	number		Signal Hame		
1 5	CD	1				
(0 0)	RD	2		SD		
6 9	SD	3		RD		
Based on	DTR	4				
communication	SG	5				
cable connector	DSR	6				
front,	RTS	7		SG		
D-SUB 9 Pin male	CTS	8				
(male, convex)		9				

^{*}Note 1) The pin arrangement is as seen from the connecting side of the cable connection connector.

■ RS-485 (1:1 connection)

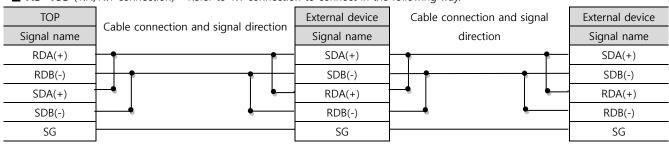
TO-405 (1.1 connection)					
TOP				External device	
Pin	Signal	Pin	Cable connection	Cianal name	
arrangement*Note 1)	name	number		Signal name	
1 5	RDA(+)	1	•	SDA(+)	
(0 0)		2	•	SDB(-)	
6 9		3] •	RDA(+)	
Based on	RDB(-)	4	 	RDB(-)	
communication	SG	5		SG	
cable connector	SDA(+)	6	 •		
front,		7			
D-SUB 9 Pin male		8			
(male, convex)	SDB(-)	9			

^{*}Note 1) The pin arrangement is as seen from the connecting side of the cable connection connector.

■ RS-422 (1:N connection) – Refer to 1:1 connection to connect in the following way.

TOP	Cable connection and cional direction	External device	Cable connection and signal	External device
Signal name	Cable connection and signal direction	Signal name	direction	Signal name
RDA(+)		SDA(+)		SDA(+)
RDB(-)		SDB(-)		SDB(-)
SDA(+)		RDA(+)		RDA(+)
SDB(-)		RDB(-)		RDB(-)
SG		SG		SG

■ RS-485 (1:N/N:1 connection) – Refer to 1:1 connection to connect in the following way.





5. Supported addresses

The devices available in TOP are as follows:

For more details on **PELCO CAMERA**, refer to the user manual.

Command	Bit address range	Word address range	R/W	Device description		
STANDARD COMMAND						
UP	0	0	W	Camera up		
DOWN	0	0	W	Camera down		
LEFT	0	0	W	Camera left		
RIGHT	0	0	W	Camera right		
UPLEFT	0	0	W	Camera up,left		
UPRIGHT	0	0	W	Camera up,right		
DOWNLEFT	0	0	W	Camera down,left		
DOWNRIGHT	0	0	W	Camera down,right		
ZOOMIN	0	0	W	Camera zoomin		
ZOOMOUT	0	0	W	Camera zoomout		
FOCUSFAR	0	0	W	Camera focus far		
FOCUSNEAR	0	0	W	Camera focus near		
STOP	0	0	W	Camera stop		
OPEN	0	0	W	Camera open		
CLOSE	0	0	W	Camera close		
ON	0	0	W	Camera on		
OFF	0	0	W	Camera off		
PANSPEED	0	0	R/W	Camera pan speed		
TILTSPEED	0	0	R/W	Camera Tilt speed		
We recommend using a command that supports the EXTENDED COMMAND (general response)						
RUN	0	0	W	User command		
COMMAND1	0	0	R/W	Create a desired command to use (not used regularly)		
COMMAND2	0	0	R/W	Create a desired command to use (not used regularly)		
DATA1	0	0	R/W	Create a desired value to use (not used regularly)		
DATA2	0	0	R/W	Create a desired value to use (not used regularly)		