OMRON Industrial Automation CompoWay/F Driver

Supported version TOP Design Studio

V1.4.9.79 or higher



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We want to thank our customers who use the Touch Operation Panel.

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Refer to this section to check the addresses which can communicate with an external device.



1. System configuration

■ The system configuration of TOP and OMRON's COMPOWAYF PROTOCOL is as follows.

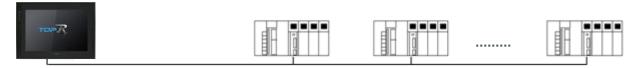
Series	Interface	Communication method	System setting	Cable
Device that supports COMPOWAY/F protocol	Serial	RS-232C RS-422/485	3. Setting example	4. Cable table

■ Connection configuration

• 1 : 1 (one TOP and one external device) connection



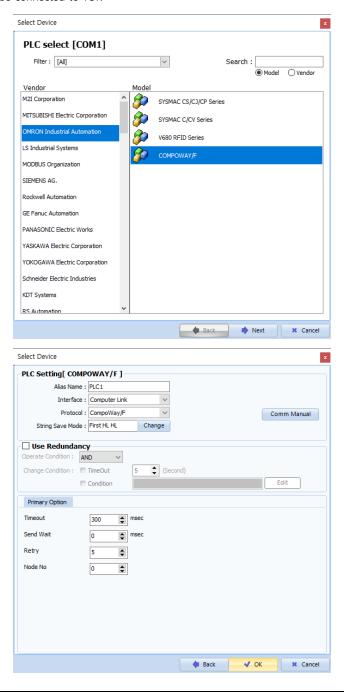
 \cdot 1 : N (one TOP and N external devices) connection – This configuration is possible in RS422 communication.





2. External device selection

■ Select an external device to be connected to TOP.



Settings		Contents				
ТОР	Model	Select the TOP model.				
	Vendor	Select the vendor of the external device. Select "OMRON Industrial Automation".				
	Model	Select an external device to connect to TOP.				
External device		Model	Interface	Protocol		
		CompoWay/F	Computer Link	CompoWay/F		
		Please check the system connect is a model whose s	•	see if the external device you want to		



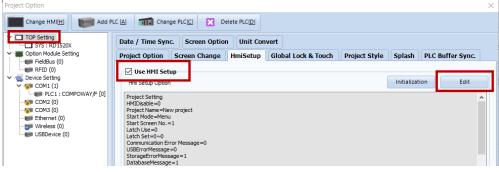
3. TOP communication setting

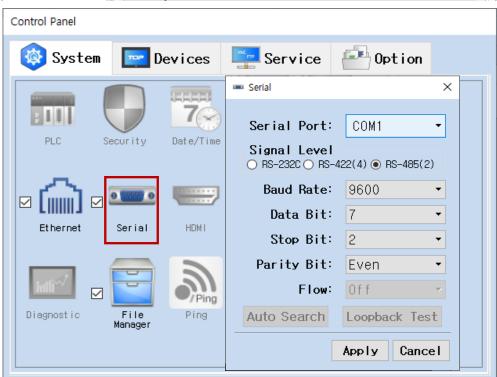
The communication can be set in TOP Design Studio or TOP main menu. The communication should be set in the same way as that of the external device.

3.1 Communication setting in TOP Design Studio

(1) Communication interface setting

- [Project > Project properties > TOP settings] → [Project option > Check "Use HMI settings" > Edit > Serial]
 - Set the TOP communication interface in TOP Design Studio.





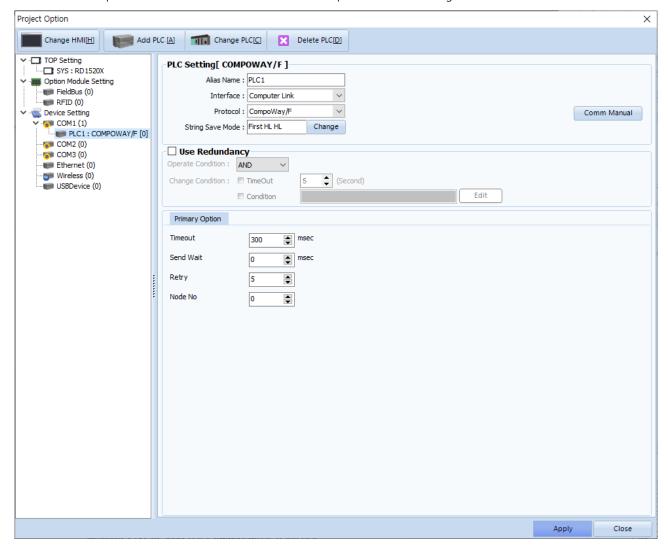
Items	ТОР	External device	Remarks
Signal Leve	RS-232C	RS-232C	
(port)	RS-422/485	RS-422/485	
Baud Rate	96		
Data Bit			
Stop Bit			
Parity Bit	Ev	en	

Items	Description
Signal Level	Select the serial communication method between the TOP and an external device. (COM 3 only supports RS-485.)
Baud Rate	Select the serial communication speed between the TOP and an external device.
Data Bit	Select the serial communication data bit between the TOP and an external device.
Stop Bit	Select the serial communication stop bit between the TOP and an external device.
Parity Bit	Select the serial communication parity bit check method between the TOP and an external device.



(2) Communication option settings

- \blacksquare [Project] → [Project property] → [Device setting → COM Port → CompoWay/F]
 - Set the options of the communication driver of the Computer Link in TOP Design Studio

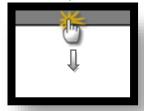


Items	Settings	Remarks
Interface	Select "Computer Link".	Refer to "2. External
Protocol	Select "Computer Link".	device selection".
TimeOut (ms)	Set the time for the TOP to wait for a response from an external device.	
SendWait (ms)	Set the waiting time between TOP's receiving a response from an external device and sending the next command request.	
Node No	Enter the prefix of an external device.	



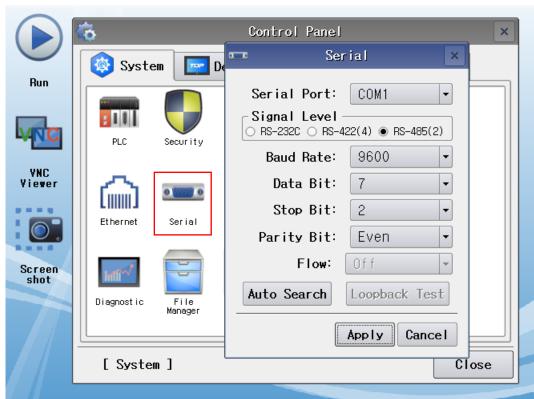
3.2 Communication setting in TOP

- * This is a setting method when "Use HMI Setup" in the setting items in "3.1 TOP Design Studio" is not checked.
- Touch the top of the TOP screen and drag it down. Touch "EXIT" in the pop-up window to go to the main screen.



(1) Communication interface setting

■ [Main screen > Control panel > Serial]



Items	TOP-R	External device	Remarks	
Signal Level	RS-232C	RS-232C		
(port)	RS-422/485	RS-422/485		
Baud Rate	9600			
Data Bit	7			
Stop Bit	2			
Parity Bit	Even			

 $^{^{\}star}$ The above settings are setting $\underline{\text{examples}}$ recommended by the company.

Items	Description
Signal Level	Select the serial communication method between the TOP and an external device. (COM 3 only supports RS-485.)
Baud Rate	Select the serial communication speed between the TOP and an external device.
Data Bit	Select the serial communication data bit between the TOP and an external device.
Stop Bit	Select the serial communication stop bit between the TOP and an external device.
Parity Bit	Select the serial communication parity bit check method between the TOP and an external device.



(2) Communication option setting

■ [Main screen > Control panel > PLC]



Items	Settings	Remarks
Interface	Select "Computer Link".	Refer to "2. External
Protocol	Select "CompoWay/F".	device selection".
TimeOut (ms)	Set the time for the TOP to wait for a response from an external device.	
Canal Mait (1000)	Set the waiting time between TOP's receiving a response from an external device	
SendWait (ms)	and sending the next command request.	
Node No	Enter the prefix of an external device.	



3.3 Communication diagnostics

- Check the interface setting status between the TOP and an external device.
- Touch the top of the TOP screen and drag it down. Touch "EXIT" in the pop-up window to go to the main screen.
- Check whether the port (COM1/COM2/COM3) settings you want to use are the same as those of the external device in [Control panel > Serial].
- Diagnosis of whether the port communication is normal or not
- Touch "Communication diagnostics" in [Control Panel > PLC].
- The Diagnostics dialog box pops up on the screen and determines the diagnostic status.

ОК	Communication setting normal
Time Out Error	Communication setting abnormal
	- Check the cable, TOP, and external device setting status. (Reference: Communication diagnostics sheet)

■ Communication diagnostics sheet

- If there is a problem with the communication connection with an external terminal, please check the settings in the sheet below.

Items	Contents		Check		Remarks
System	How to connect the system		OK	NG	1 Cystom configuration
configuration	Connection cable nam	ne	OK	NG	1. System configuration
TOP	Version information	Version information			
	Port in use		OK	NG	
	Driver name		OK	NG	
	Other detailed setting	S	OK	NG	
	Relative prefix	Project setting	OK	NG	
		Communication diagnostics	ОК	NG	2. Select an external device3. Communication setting
	Serial Parameter	Transmission Speed	OK	NG	
		Data Bit	OK	NG	
		Stop Bit	OK	NG	
		Parity Bit	OK	NG	
External device	CPU name	OK	NG		
	Communication port	OK	NG		
	Protocol (mode)	OK	NG		
	Setup Prefix	OK	NG		
	Other detailed setting	Other detailed settings			
	Serial Parameter	Transmission	OK	NG	
		Speed	UK	ING	
		Data Bit	OK	NG	
		Stop Bit	OK	NG	
		Parity Bit	OK	NG	
	Check address range		ОК	NG	5. Supported address (For details, refer to the PLC manufacturer's manual.)



4. Cable table

This chapter introduces a cable diagram for normal communication between the TOP and the corresponding device. (The cable diagram described in this section may differ from the recommendations of "OMRON Industrial Automation")

4.1. Cable table 1

■ RS-232C (1:1 connection)

COM1 / COM2				PLC		
Pin	Signal	Pin	Cable connection	Pin	Signal	Pin
arrangement*Note 1)	name	number		number	name	arrangement*Note 1)
1 5	RD	2		2	SD	1 5
$(\circ \circ)$	SD	3		3	RD	0 0
6	SG	5		5	RS	0
6 9				7	CS	6 9
Based on				8	SG	Based on
communication						communication
cable connector						cable connector
front,						front,
D-SUB 9 Pin male						D-SUB 9 Pin male
(male, convex)						(male, convex)

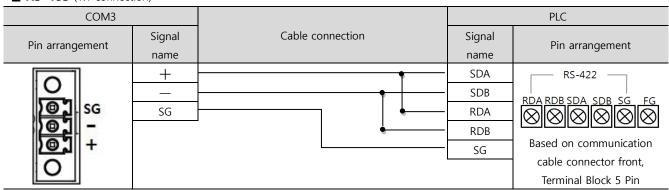
^{*}Note 1) The pin arrangement is as seen from the connecting side of the cable connection connector.

■ RS-422 (1:1 connection)

COM1,	COM2				PLC
Pin	Signal	Pin	Cable connection	Signal	Din arrangemental (4)
arrangement*Note 1)	name	number		name	Pin arrangement*Note 1)
1 5	RDA	1 .		RDA	
(0 0)	RDB	4		RDB	RS-422 —
(<u>)</u>	SDA	6		SDA	R3-422
6 9	SDB	9 -		SDB	RDA RDB SDA SDB SG FG
Based on				SG	
communication					Based on communication
cable connector					cable connector front,
front,					Terminal Block 5 Pin
D-SUB 9 Pin male					
(male, convex)					

*Note 1) The pin arrangement is as seen from the connecting side of the cable connection connector.

■ **RS-485** (1:1 connection)





5. Supported addresses

The devices available in TOP are as follows:

The device range (address) may differ depending on the CPU module series/type. The TOP series supports the maximum address range used by the external device series. Please refer to each CPU module user manual and be take caution to not deviate from the address range supported by the device you want to use.

Device	Bit Address	Word Address	NOTE
40	40-0000.00~C0FFFF.31	40-0000~C0FFFF	
4000	4000-0000.00 ~ 4000-FFFF.31	4000-0000 ~ 4000-FFFF	
80	80-0000.00~C0FFFF.31	80-0000~C0FFFF	Different devices have different features.
8000	8000-0000.00 ~ 8000-FFFF.31	8000-0000 ~ 8000-FFFF	
C0	C0-0000.00~C0FFF.31	C0-0000~C0FFFF	
C1	C1-0000.00~C1FFFF.31	C1-0000~C1FFFF	
C2	C2-0000.00~C2FFFF.31	C2-0000~C2FFFF	
C3	C3-0000.00~C3FFFF.31	C3-0000~C3FFFF	
C4	C4-0000.00~C3FFFF.31	C4-0000~C3FFFF	
C5	C5-0000.00~C3FFFF.31	C5-0000~C3FFFF	
C6	C6-0000.00~C3FFFF.31	C6-0000~C3FFFF	
C7	C7-0000.00~C3FFFF.31	C7-0000~C3FFFF	
C8	C8-0000.00~C3FFFF.31	C8-0000~C3FFFF	
C9	C9-0000.00~C3FFFF.31	C9-0000~C3FFFF	
CA	CA-0000.00~CAFFFF31	CA-0000~CAFFFF	
СВ	CB-0000.00~CBFFFF.31	CB-0000~CBFFFF	
СВ	CC-0000.00~CBFFFF.31	CC-0000~CBFFFF	
СВ	CD-0000.00~CBFFFF.31	CD-0000~CBFFFF	
СВ	CE-0000.00~CBFFFF.31	CE-0000~CBFFFF	
СВ	CF-0000.00~CBFFFF.31	CF-0000~CBFFFF	
D0	D0-0000.00~D0FFF.31	D0-0000~D0FFFF	
D1	D1-0000.00~D1FFFF.31	D1-0000~D1FFFF	
D4	D4-0000.00~D4FFF.31	D4-0000~D4FFFF	
D5	D5-0000.00~D5FFFF.31	D5-0000~D5FFFF	
D6	D6-0000.00~D6FFFF.31	D6-0000~D6FFFF	
D7	D7-0000.00~D7FFFF.31	D7-0000~D7FFFF	
D8	D8-0000.00~D8FFFF.31	D8-0000~D8FFFF	
D9	D9-0000.00~D8FFFF.31	D9-0000~D8FFFF	
DA	DA-0000.00~D8FFFF.31	DA-0000~D8FFFF	
DB	DB-0000.00~D8FFFF.31	DB-0000~D8FFFF	
DC	DC-0000.00~D8FFFF.31	DC-0000~D8FFFF	
DD	DD-0000.00~D8FFFF.31	DD-0000~D8FFFF	
DE	DE-0000.00~D8FFFF.31	DE-0000~D8FFFF	
DF	DF-0000.00~D8FFFF.31	DF-0000~D8FFFF	
E0	E0-0000.00~E0FFFF.31	E0-0000~E0FFFF	
E1	E1-0000.00~E1FFFF.31	E1-0000~E1FFFF	
C000	C000-0000.00 ~ C000-FFFF.31	C000-0000 ~ C000-FFFF	
COMMAND			Different devices have
		COMMAND-00 ~COMMAND-FF	different features.
		CONTINIATION ~ CONTINIATION FFF	Refer to the COMMAND description.
			Merer to the Conviniand description.



****** COMMAND Address description

For COMMAND address, only write operations are possible.

Use the COMMAND address to send special action commands. (COMMAND 3005)

The address number of COMMAND registered in the object becomes the command code, and the input value is transmitted as the motion content.

COMMAND address	Data of the COMMAND address
Command code	Motion content

COMMAND-[command code] = [motion content]

For external device OMRON E5CN

When entering 0 in COMMAND-[01] \rightarrow Run motion

When entering 1 in COMMAND-[01] \rightarrow Stop motion

When entering 0 in COMMAND-[04] → Backup mode

When entering 1 in COMMAND-[09] → Manual mode

*. The COMMAND is different for each device, so refer to the manual of each device.

% Write-only Device Use Method

[Object's property window pop-up] \rightarrow [Effects and Motions] \rightarrow [Condition settings] \rightarrow [Motion settings \rightarrow Word \rightarrow COMMAND-[Command code]]

Set to input data (motion content) to the corresponding device when setting the motion.

